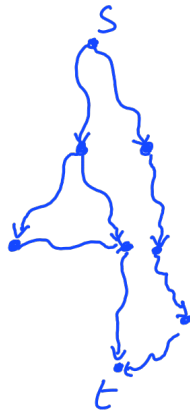
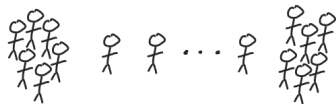


# Parameterized Flows

Joint work with Hugo Gimbert  
and Patrick Totzke



PaVeDys  
Mai 2025

# Model

Finite set of states  $S$

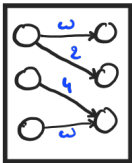
$q_1$  ○

$q_2$  ○

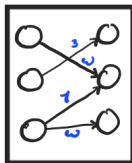
$q_3$  ○

Finite set of tiles

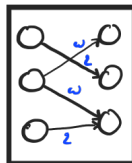
$\tau$



$a$



$b$



$c$

# Model

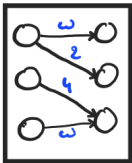
Finite set of states  $S$

$q_1$  ○

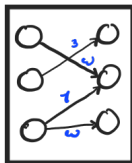
$q_2$  ○

$q_3$  ○

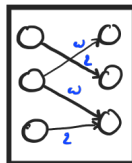
Finite set of tiles  $\tau$



a



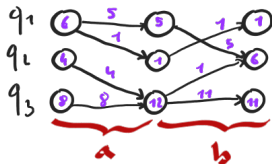
b

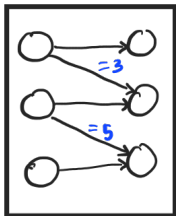


c

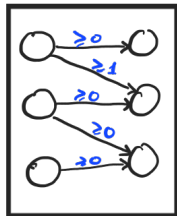
Configurations =  $\mathbb{N}^S$

Step = transfer of tokens  $\leq x \in \tau$

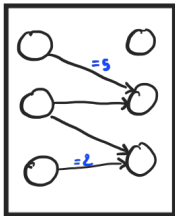




$\approx$  VASS

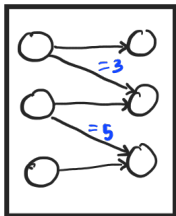


$\approx$  Lossy Broadcast.

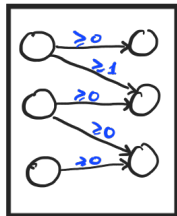


$\approx$  VASS  
with 0-test

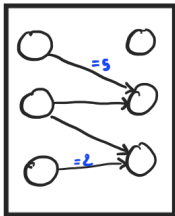
$\approx$  Reliable Broadcast



$\approx$  VASS

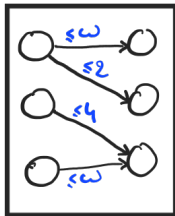


$\approx$  Lossy Broadcast.



$\approx$  VASS  
with 0-test

$\approx$  Reliable Broadcast



$\approx$  Locks?

# Sequential Flow Problem [Colcombet, Fijalkow, Ohlmann '20]

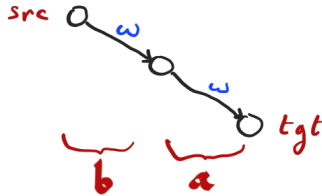
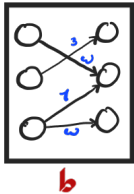
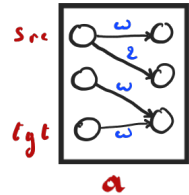
Input: Finite set of tiles  $\tau \in (N \cup \{v\})^{S \times S}$   
Source state  $src \in S$   
Target state  $tgt \in S$

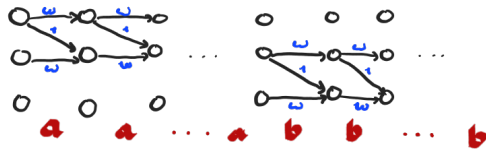
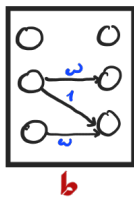
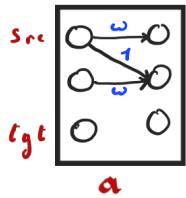
Question:  $\forall N \in N$ ,  
there is a path from  $(N \cdot src)$  to  $(N \cdot tgt)$ ?

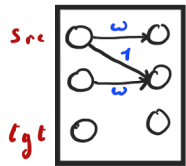
# Sequential Flow Problem [Colcombet, Fijalkow, Ohlmann '20]

**Input:** Finite set of tiles  $\tau \in (N \cup \{w\})^{S \times S}$   
Source state  $src \in S$   
Target state  $tgt \in S$

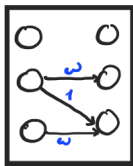
**Question:**  $\forall N \in \mathbb{N}$ ,  
there is a path from  $(N \cdot src)$  to  $(N \cdot tgt)$ ?



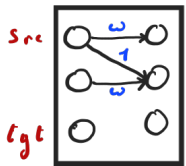
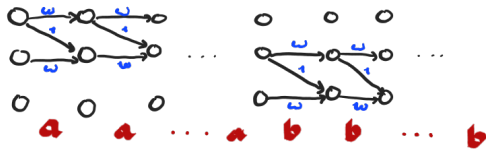




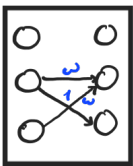
a



b

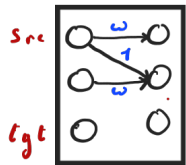


a

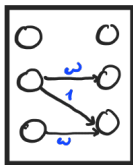


b

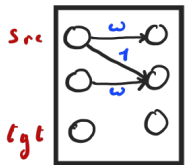
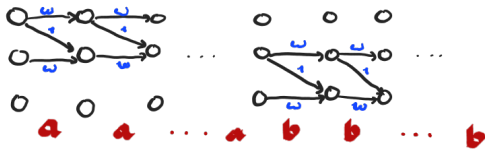




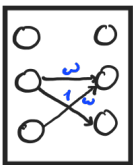
a



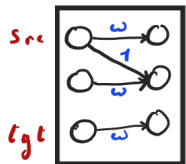
b



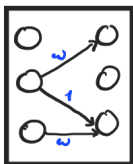
a



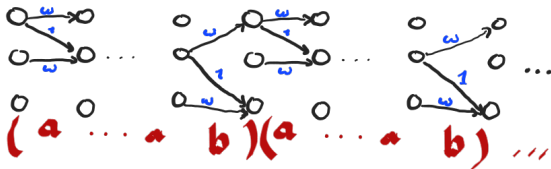
b



a



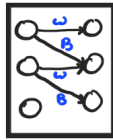
b



# Monoid abstraction $M$

$1, 2, 3, \dots \rightsquigarrow \mathcal{B}$

Elements :

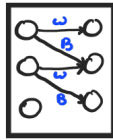


$\{0, B, \omega\}^{S \times S}$

# Monoid abstraction $\mathcal{M}$

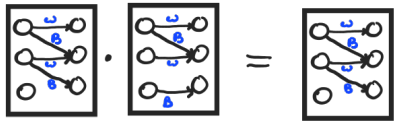
$1, 2, 3, \dots \rightsquigarrow \mathcal{B}$

Elements :



$\{0, \mathcal{B}, \omega\}^{S \times S}$

Product = max-min  $\rightsquigarrow (\tau_1 \cdot \tau_2)[s, s'] = \max_{s'' \in S} \min(\tau_1[s, s''], \tau_2[s'', s'])$

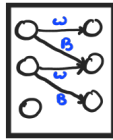


Morphism  $\tau^* \rightsquigarrow \mathcal{M}$

# Monoid abstraction $M$

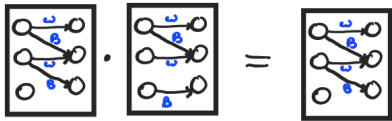
$1, 2, 3, \dots \rightsquigarrow B$

Elements :



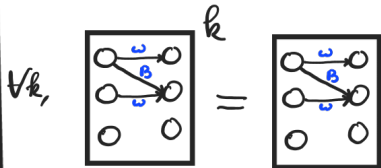
$\{0, B, w\}^{S \times S}$

Product = max-min  $\rightsquigarrow (\tau_1 \cdot \tau_2)[s, s'] = \max_{s'' \in S} \min(\tau_1[s, s''], \tau_2[s'', s'])$



Morphism  $\tau^* \rightsquigarrow M$

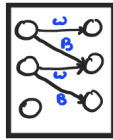
⚠ Problem :



# Monoid abstraction $M$

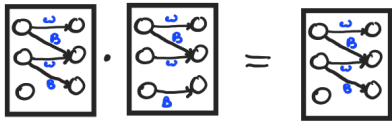
$1, 2, 3, \dots \rightsquigarrow B$

Elements :



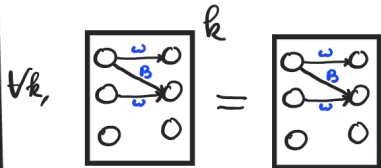
$\{0, B, w\}^{S \times S}$

Product = max-min  $\rightsquigarrow (\tau_1 \cdot \tau_2)[s, s'] = \max_{s'' \in S} \min(\tau_1[s, s''], \tau_2[s'', s'])$

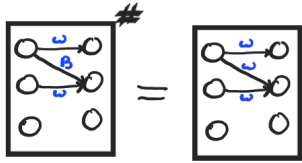


Morphism  $\tau^* \rightsquigarrow M$

⚠ Problem :



Define an operator  $\varphi$  (on idempotents)



Morphism  $\varphi$  from #expressions to  $M$   
 $(a \# b) \#$

If there is a #expression  $E$   
 such that  $\varphi(E)[src, tgt] = \omega$  then return Yes

↳ For all  $N$ , we can transfer  $N$  tokens  
 by replacing  $\#$  with  $N$ .

$(a^N b)^N$

# Simon's theorem

- Finite monoid  $M$
- Alphabet  $\Sigma$
- Morphism  $\varphi: \Sigma^* \rightarrow M$

Factorisation tree for  $w \in \Sigma^*$   
 $M$ -labelled tree

Leaves:  $w$

Nodes: Product nodes



Iteration nodes



# Simon's theorem

- Finite monoid  $M$
- Alphabet  $\Sigma$
- Morphism  $\varphi: \Sigma^* \rightarrow M$

Factorisation tree for  $w \in \Sigma^*$

$M$ -labelled tree

Leaves =  $w$

Nodes: Product nodes



Iteration nodes



*Théorème*

$\forall w \in \Sigma^*$ , there is a factorisation tree for  $w$  of height  $\leq 3|M|$

# Application

If there is no expression  $E$   
such that  $\varphi(E)[src, tgt] = \omega$  then return  $N_D$

↳ Every word can be evaluated by  
a tree of height  $\leq 3|M|$

↳ Show that a word evaluated  
by a tree of height  $h$   
has flow  $\leq g(h, |M|)$

# Application

If there is no #expression  $E$   
such that  $\varphi(E)[src, tgt] = \omega$  then return  $N_0$

↳ Every word can be evaluated by  
a tree of height  $\leq 3|M|$

↳ Show that a word evaluated  
by a tree of height  $h$   
has flow  $\leq g(h, |M|)$

**Théorème**

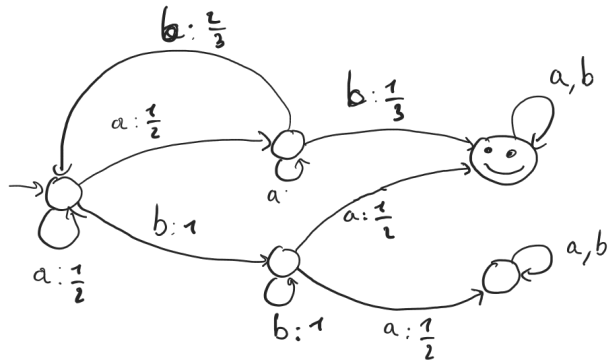
(by Saturation)

The parameterized flow problem is in EXPTIME

Application

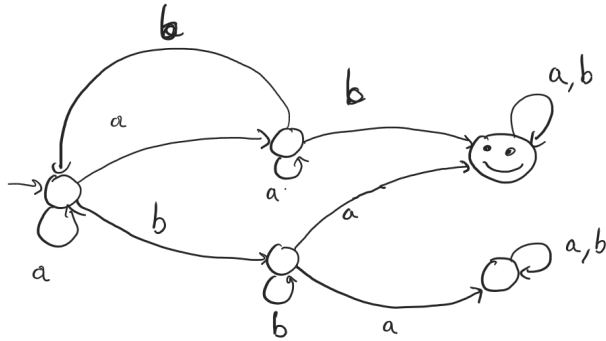
Parameterized  $\Pi DP_s$ .

Almost-sure reachability.



Goal: reach 😊 with probability 1.

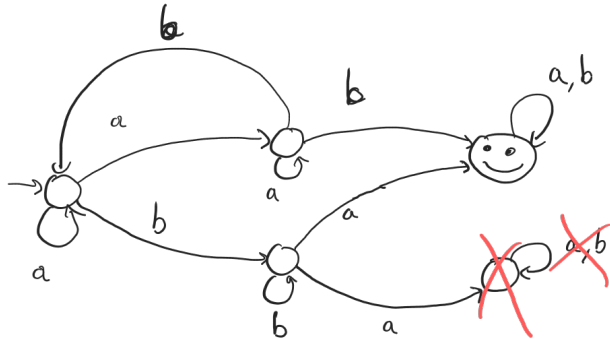
Almost-sure reachability.



→ Erase probabilities

Goal: reach 😊 with probability 1.

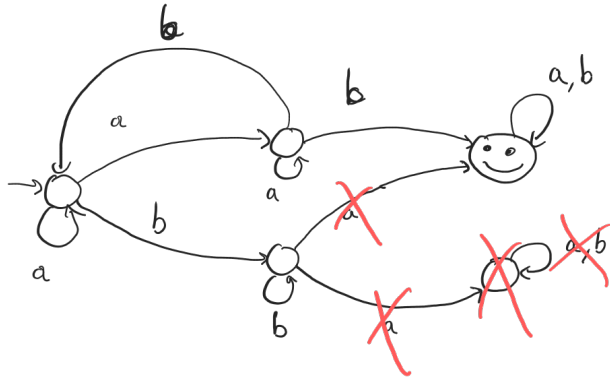
Almost-sure reachability.



Goal: reach 😊 with probability 1.

- Erase probabilities
- Compute winning region as greatest fix-point.
  - ↳ Repeatedly remove states from which 😊 is not reachable.

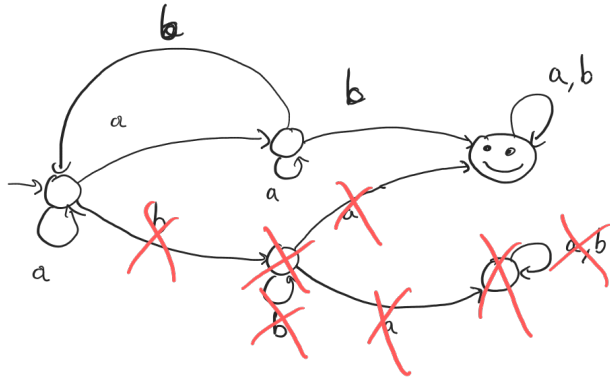
Almost-sure reachability.



Goal: reach ☺ with probability 1.

- Erase probabilities
- Compute winning region as greatest fix-point.
  - ↳ Repeatedly remove states from which ☺ is not reachable.

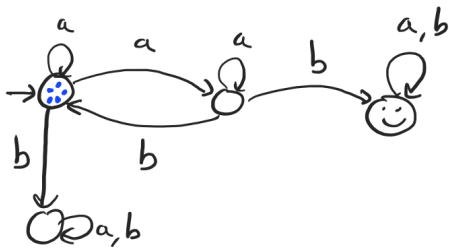
Almost-sure reachability.



Goal: reach 😊 with probability 1.

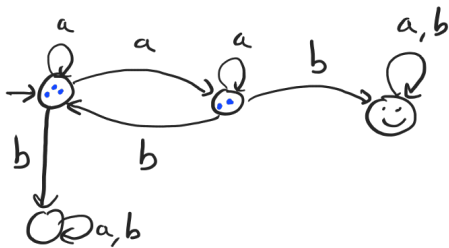
- Erase probabilities
- Compute winning region as greatest fix-point.
  - ↳ Repeatedly remove states from which 😊 is not reachable.

## Parameterized MDPs



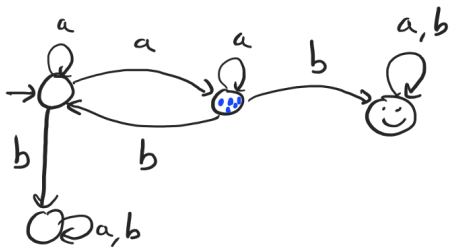
- Put  $N$  tokens in the initial state
- Each token reacts independently to the selected action.
- Try to make them all reach 😊

## Parameterized MDPs



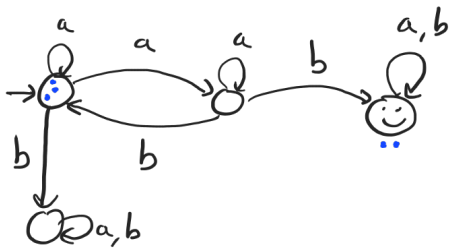
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# Parameterized MDPs



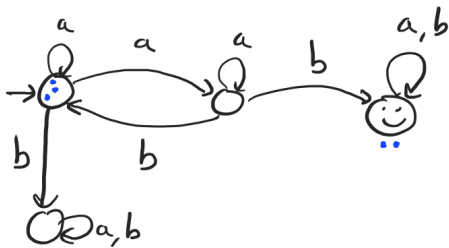
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## Parameterized MDPs

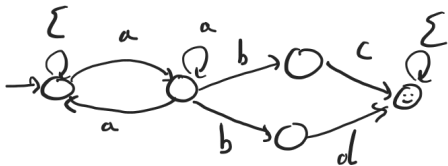


- Put  $N$  tokens in the initial state
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# Parameterized MDPs



- Put  $N$  tokens in the initial state
- Each token reacts independently to the selected action.
- Try to make them all reach 😊



# Characterisation of winning MDPs

Winning region  $\rightarrow$   $\odot$  is always reachable with proba  $> 0$ .  
 $\rightarrow$  Never leave the region

+ Winning region is  $\downarrow$ -closed

$\exists$  winning strategy

$(\Rightarrow)$

$\exists W \subseteq N^S \times \Sigma$

- $W$  is  $\downarrow$ -closed
- $\forall (v, a) \in W$ , if  $v \xrightarrow{a} v'$  then  $v' \in W$
- $\forall v \in W$ ,  $\exists$  a path  $v \rightsquigarrow F$  in  $W$
- $N \cdot \text{init} \subseteq W$

$W \leftarrow N^S \times \Sigma$

Do

    If  $\exists (v, a) \in W, v \xrightarrow{a} v'$  with  $v' \notin W$  ①

        |  $W \leftarrow W \cup v'$

    If  $\exists v \in W, v \xrightarrow{a} F$  in  $W$  ②

        |  $W \leftarrow W \cup v$

Until fixpoint

If  $I \subseteq W \rightarrow \text{Yes}$

Else  $\rightarrow \text{No}$

①  $\rightarrow$  Easy

②  $\rightarrow$  Sequential flow problem

## Theorem

The Random population control problem is EXPTIME-complete.

Proof: Show that

winning strat  $\Rightarrow \exists$  a region within the winning region in which at all times we have

- $\hookrightarrow$  large crowds of tokens  $\omega$
- $\hookrightarrow$  small sets of isolated tokens  $\leq |S|$

# Future work

Applications to - Verification  
- Flows in infinite graphs

Quantitative objectives for parameterized MDPs

Speed of victory                   "                   "                   "